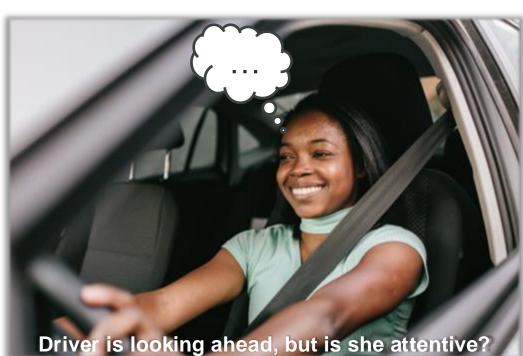
A Novel Paradigm for Identifying Eye-Tracking Metrics Associated with Cognitive Control During Driving Through MEG Neuroimaging

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Introduction

- *Inattention* a leading cause of crashes for young drivers. (Curry et al., 2011; Lestina & Miller, 1994; McKnight & McKnight, 2003; Seacrist et al., 2021)
- Attributable to limited frontal-lobe cognitive abilities that are still developing throughout adolescence (Satterthwaite et al., 2013)
- External distractions are easier to detect with driver monitoring
- **Cognitive inattention more difficult** • "Look but do not see"



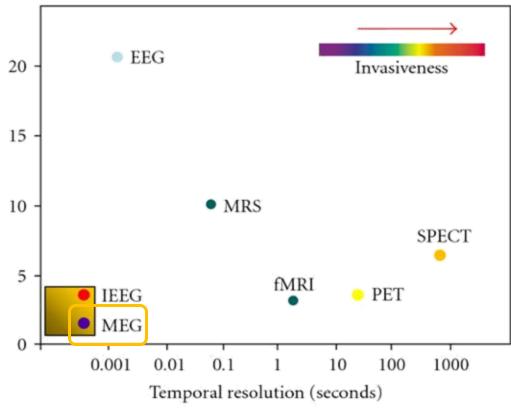
- Need to identify metrics that indicate top-down cognitive control during driving
- Identify *absence* of cognitive control during safety critical events

Objectives

Demonstrate the utility of MEG neuroimaging to identify eyetracking metrics that proxy periods of increased cognitive control during driving

Magnetoencephalography (MEG)

- Magnetoencephalography (MEG) is *non-invasive* and exhibits high spatial and temporal resolution
- Identify frequency-specific and precise location of brain activity
- Use to identify periods of elevated frontal midline theta (FMT) activity (3-9 Hz) during driving
- FMT an established *marker of cognitive control* over behavior (Callaghan et al. 2017)



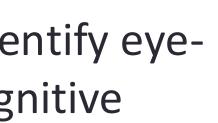
MEG + Eye-Tracking + Driving





Participants seated in a CTF-Omega 275 Channel MEG (600 Hz) Included MEG-compatible eye-tracker (SR Research EyeLink 1000; 1000) Hz) and driving hardware (Current Designs, Inc.)

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Methods

POPULATION

 Typically developing adolescents (12-17 yrs) were recruited.

Participa

SIMULATED DRIVE

• Participants drove a *Basic Braking Task*, designed to elicit increased FMT activity when actively braking for the red light. Repeated for 20 trials





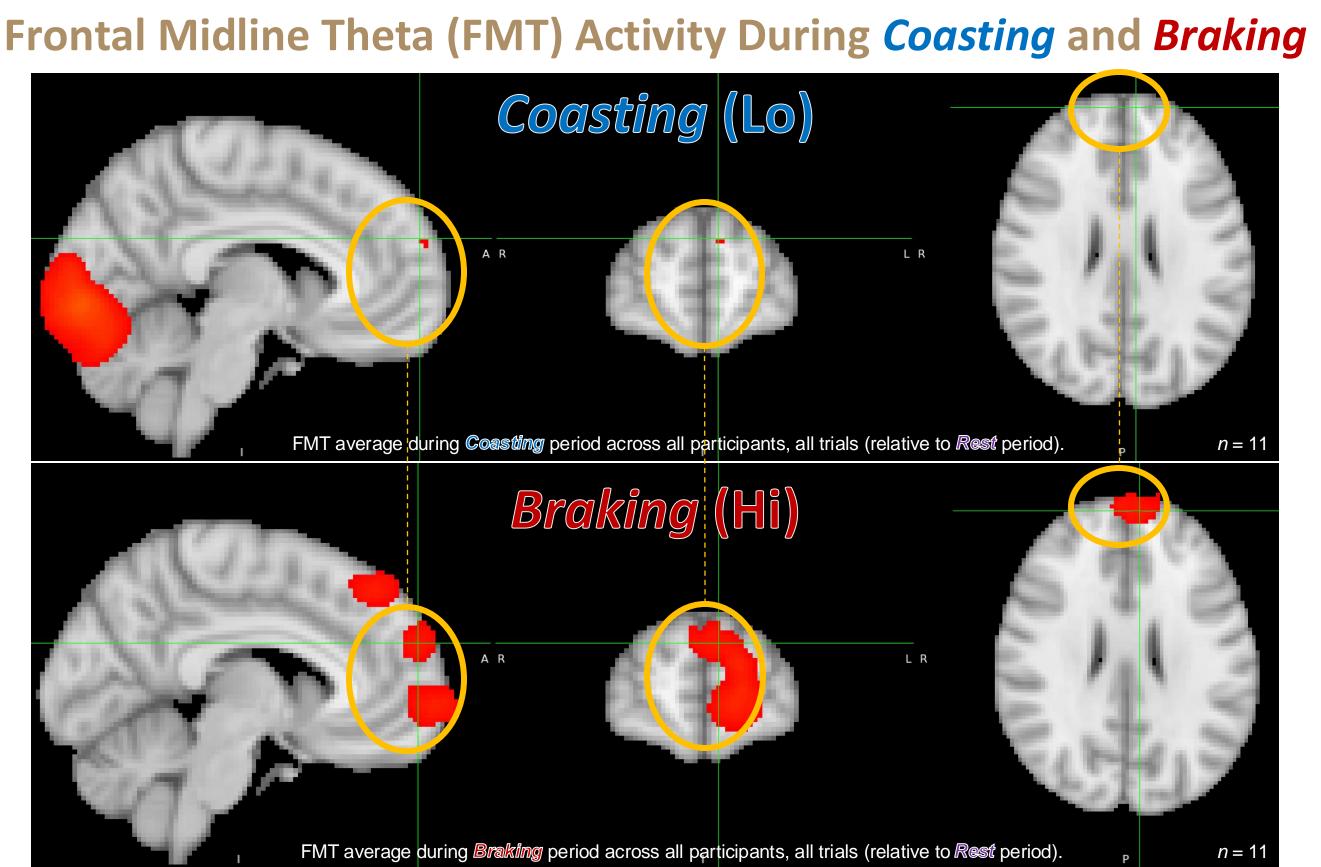
next intersection.

Drive begins with a 9 sec *Rest* period.

DATA ANALYSIS

- FMT and eye-tracking metrics compared between: *Coasting* – 4 sec of steady-state
- driving, requiring minimal (Lo) top-down cognitive control **Braking** – 4 sec of active braking
- at red light, requiring elevated (Hi) top-down cognitive control
- Eye-tracking metrics compared between *Coasting* (Lo) and **Braking** (Hi) using paired t-tests

Results – Neuroimaging



Increased FMT was observed during *Braking* (Hi), relative to *Coasting* (Lo)

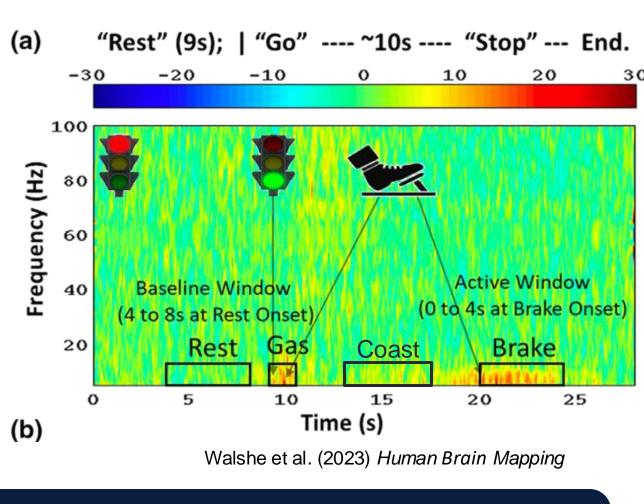
Population Demographics

	n		Sex
ants	11	15.1 ±	4 Female
		1.5 yrs	7 Male





Come to a stop at next red light.



Results – Eye-Tracking

Mean (±SD) Eye-Tracking Metrics Between *Coasting* and *Braking*

Metric			
ixation Coun			

- **Fixation Duration**
 - Mean Gaze
 - (Horizontal)
 - Mean Gaze (Vertical)
- Spread of Search (Horizontal)
- Spread of Search (Vertical)

Exemplar Scan Paths During *Coasting* (Lo) and *Braking* (Hi)



Conclusions

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Unit	Coasting (Lo)	Braking (Hi)	<i>p</i> -value
#	12 ± 3	10 ± 4	0.02
ms	339 ± 125	429 ± 146	0.06
pxls	839 ± 55	932 ± 72	0.00
pxls	738 ± 58	652 ± 100	0.00
pxls	160 ± 33	147 ± 59	0.46
pxls	174 ± 24	147 ± 38	0.04

• Drivers exhibited *narrower* vertical spread of search during *Braking* (Hi) Indicative of narrower, more focused scanning

Higher vertical *mean gaze* and lower *fixation count* during *Braking* (Hi) • Focused on traffic signals and intersection ahead; less on speedometer

Iorizontal Position (px

Exemplar scan path from a single driver, single trial during Coasting (Lo) (left) and Braking (Hi) (right) Circles represent fixations; diameter proportional to duration

Findings suggest that eye-tracking metrics may be a useful proxy for periods of cognitive control during driving.

Data will help OEMs optimize driver monitoring to *detect* absence of top-down cognitive control in real-time.